

KLEPPNER & KOLENKOW ERRATA

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This is a list of typos from An Introduction to Mechanics by Daniel Kleppner and Robert Kolenkow compiled for Physics H7A at UC Berkeley. To reach the compiler, please email Joel Corbo at jcorbo@berkeley.edu. Thanks to all those who have contributed to this list.

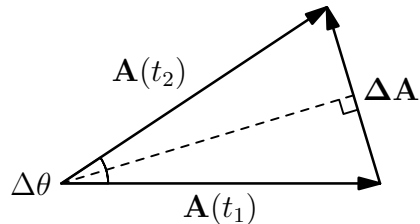
Chapter 1: Vectors and Kinematics

- Page 17, Example 1.7

In the figure at the top of the page, the labels $\mathbf{r}(0)$ and $\mathbf{r}(t)$ on the position vectors have been inverted.

- Page 26, Section 1.9

In the line “Using the angle $\Delta\theta$ defined in the sketch,” there is no such sketch. This is my best guess as to what was intended:



- Page 42, Notes 1.1

The first equation in the Taylor’s Series section should read:

$$f(x) = a_0 + a_1x + a_2x^2 + \cdots = \sum_{k=0}^{\infty} a_k x^k.$$

- Page 48, Problem 1.13

Replace the first sentence of the problem with “At $t = 0$, an elevator departs from the ground with uniform speed.”

- Page 49, Problem 1.19

Replace the first sentence of the problem with “A tire of radius R rolls in a straight line without slipping.”

Chapter 2: Newton's Laws

- *Page 103, Problem 2.1*

Replace the second sentence of the problem with, “It starts at rest from the origin at $t = 0$.”

- *Page 105, Problem 2.17b*

The second sentence should begin, “Assuming that $\tan \theta > \mu$,” not “Assuming that $\tan \theta < \mu$.”

Chapter 3: Momentum

- *Page 129, Example 3.8*

The very first sentence on the page should be replaced with, “The instantaneous length of the spring is $r_a - r_b = r'_a - r'_b$. The instantaneous departure of the spring from its equilibrium length is $r_a - r_b - l = r'_a - r'_b - l$, where l is the unstretched length of the spring.”

- *Page 131, Example 3.9*

In the last sentence of the second paragraph, replace “If the ball hits a resilient surface” with “If the ball hits a softer surface”.

- *Page 137, Section 3.5*

Towards the bottom of the page, replace the section beginning with “The change in momentum is” and ending with equation 3.18 to:

The change in momentum is

$$\begin{aligned}\Delta \mathbf{P} &= \mathbf{P}(t + \Delta t) - \mathbf{P}(t) \\ &= M\Delta \mathbf{v} + (\Delta m)\mathbf{u} + \Delta m\Delta \mathbf{u}\end{aligned}$$

Therefore,

$$\begin{aligned}\frac{d\mathbf{P}}{dt} &= \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{P}}{\Delta t} \\ &= \lim_{\Delta t \rightarrow 0} \left(M\frac{\Delta \mathbf{v}}{\Delta t} + \mathbf{u}\frac{\Delta m}{\Delta t} + \frac{\Delta m\Delta \mathbf{u}}{\Delta t} \right) \\ &= M\frac{d\mathbf{v}}{dt} + \mathbf{u}\frac{dm}{dt}.\end{aligned}\tag{3.18}$$

- *Page 149, Problem 3.17*

In the answer clue, the weight W should be equal to 8.2 N, not 10 kg.

Chapter 4: Work and Energy

- *Page 157, Example 4.3*

The left-hand side of the second equation on the page should read “ $K(r) - K(R_e)$ ”, not “ $K(r) - K(r_e)$ ”.

- *Page 161, Section 4.5*

The line after equation 4.15 should read, “where $\mathbf{V} = \dot{\mathbf{R}}$ is the velocity of the center of mass.”

- *Page 164, Example 4.6*

About half way down the page, replace each instance of φ with ϕ in the equations after “The work done by gravity is”. (Note that these two symbols are different ways to write the Greek letter phi.)

Chapter 5: Some Mathematical Aspects of Force and Energy

- *Page 205, Example 5.2*

In the equation below “The differential of f is,” replace the first dy with dx , producing $df = \frac{\partial(xy)}{\partial x} dx + \frac{\partial(xy)}{\partial y} dy$.

Chapter 6: Angular Momentum and Fixed Axis Rotation

- *Page 237, Example 6.2*

The last equation on the page should read $\mathbf{L}_A = Mr^2\omega\hat{\mathbf{k}}$.

- *Page 242, Example 6.4*

The second sentence in the second-to-last paragraph on the page should begin “The total energy $E = K + U$ is”.

- *Page 261, Section 6.7*

The second line of the set of equations after “Eliminating \mathbf{r}_j from Eq. (6.9) gives” should read $\Sigma(\mathbf{R} + \mathbf{r}'_j) \times m_j(\dot{\mathbf{R}} + \dot{\mathbf{r}}'_j)$.

- *Page 276, Note 6.2*

In the equation following $E = K + U$, the term $\frac{1}{2}l^2\dot{\phi}^2$ should read $\frac{1}{2}ml^2\dot{\phi}^2$.

- *Page 282, Problem 6.23*

The answer clue should read, “If $A = 2a$, then $\alpha = \frac{3a}{R}$.”

Chapter 7: Rigid Body Motion

- *Page 294, Example 7.5*

About a third of the way down the page, the equations after “The torque is” should read:

$$\begin{aligned}\tau &= \frac{d\mathbf{L}}{dt} \\ &= L\omega \sin \alpha (-\hat{\mathbf{i}} \sin \omega t + \hat{\mathbf{j}} \cos \omega t).\end{aligned}$$

- *Page 336, Problem 7.8b*

The inequality should read $F \ll \frac{2Mv^2}{b}$, not $F \ll \frac{Mv^2}{b}$.

Chapter 8: Noninertial Systems and Fictitious Forces

- *Page 362, Example 8.8*

Delete the first instance of the equation “ $F_\theta = -2mr\dot{\Omega}$ ” that appears on this page.

- *Page 371, Note 8.2*

The equation between equations 3 and 4 should read $\left(\frac{d\mathbf{B}}{dt}\right) = \frac{d}{dt}(B_x\hat{\mathbf{i}} + B_y\hat{\mathbf{j}} + B_z\hat{\mathbf{k}})$.

Chapter 9: Central Force Motion

- *Page 381, Section 9.3*

In the paragraph after equation 9.11, change the second line to, “to simply as the *effective potential*. U_{eff} differs from the true.”

- *Page 383, Section 9.4*

The sentence just before the end of the section should refer to Eqs. (9.17*a* and *b*), not Eqs. (9.16*a* and *b*), which do not exist.

- *Page 392, Equation 9.22*

In equation 9.22, the term $(1 - \epsilon^2)x$ should read $(1 - \epsilon^2)x^2$

- *Page 394, Example 9.4*

The equation at the top of the page should be replaced with $\cos \theta_a = \frac{1}{\epsilon}$.

- *Page 396, Example 9.5*

In the line after “Knowing A , we can find E from Eq. (9.26):”, change the equation after the word “or” to $E = -\frac{C}{A}$.

- *Page 406, Problem 9.3*

Replace the last sentence of the problem with, “Find θ as a function of r for motion with uniform radial velocity v .”

Chapter 10: The Harmonic Oscillator

- *Page 419, Example 10.2*

At the end of the first set of calculations, the result should be approximately 7000, not approximately 700.

- *Page 427, Section 10.3*

The last sentence before the plot should read “ γ is given in units of s^{-1} .”

- *Page 438, Problem 10.3*

In the figure accompanying this problem, replace the symbol φ with ϕ .